# Airborne Remote Sensing Component of Marine Debris Monitoring

Dr. Thomas H Mace

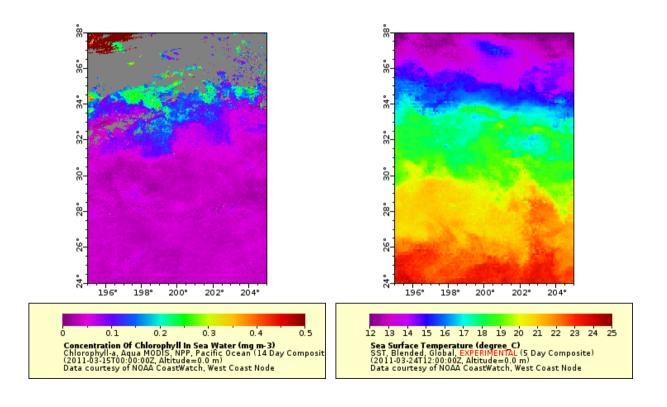
Mace Geospatial, LLC

Workshop on Mission Concepts for Marine Debris Sensing Honolulu, Hi, Jan 19-21, 2016

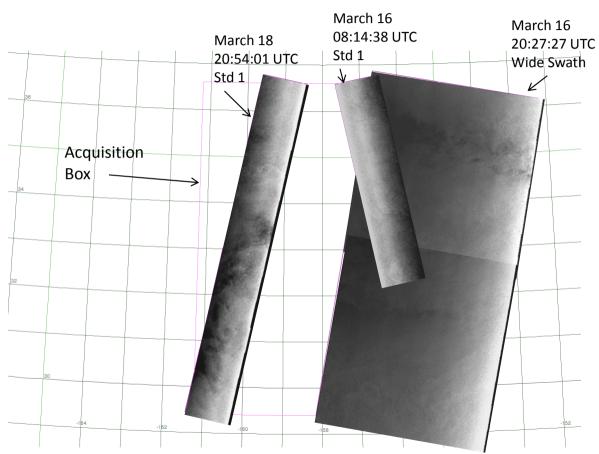
## Multistage Remote Sensing Concept

- 1. Use model and satellite data to determine convergence zones and airborne flight target areas
- 2. Use Airborne Radar and air-ship telemetry to define fine features of likely concentration of marine debris for ship search
- 3. Use ship and small UAS to spot and retrieve debris.

# MODIS and SST Satellite Interpretations



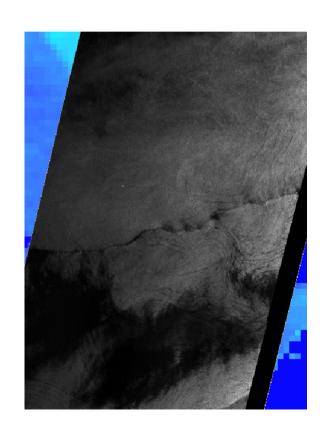
#### Envisat – March 16 – March 18



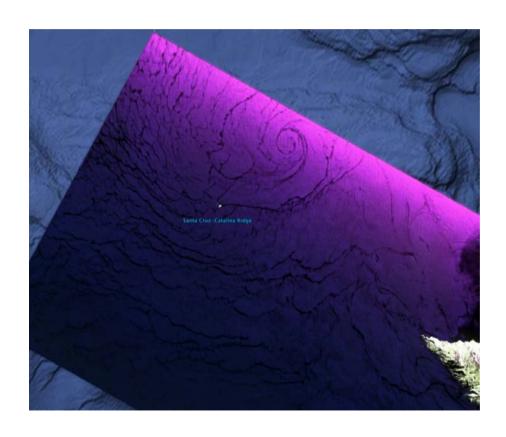
Std= standard beams, 100 km wide swath, 25 m resolution Wide Swath = 400 km wide swath, 150 m resolution

Ben Holt - JPL

# Satellite SAR image showing eddy lines



UAVSAR polarimetric three-color composite image of currents and eddies in the Santa Barbara Channel acquired on September 16, 2009, from the NASA G-III aircraft overlain on Google Earth image (Image courtesy B Holt & Y Lou – JPL).



# **Gulfstream III**UAV Synthetic Aperture Radar (UAVSAR)

### **Capabilities**

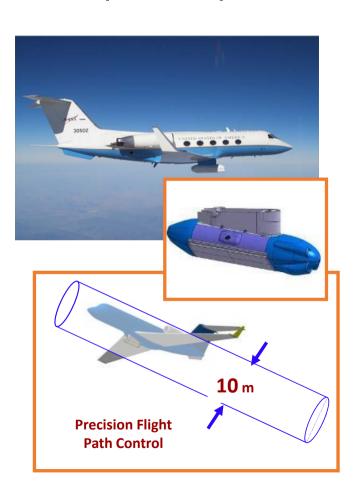
- Ceiling 45,000 ft.
- Duration 6 hours
- Range > 3,400 nautical miles
- Payload 2,610 lbs

### Mission Support Features

- Center-line pod/pylon supports UAVSAR instrument
- · Precision flight path capability
- Shirtsleeve environment instrument support
- World-wide deployment capability

#### **UAVSAR**

- Repeat-pass interferometry
- Ka-, P- and L-band capability (separate pods)
- Designed for UAV simulation



# April, 2011 Mission/Feasibility Study

- Satellite Imagery for planning
- USCG C-130 for low altitude visual confirmation of debris
- G-III interprets real time imagery onboard and sends coordinates to C-130 via base station and satphone
- Mission cancelled due to instrument failure
- We returned to Hawaii in May, but it was too late for environmental conditions

# DC-8 Flying Laboratory Large Capacity, Long Range and Endurance

### **Capabilities**

- Ceiling 42,000 ft.
- Duration 12 hours
- Range > 5,400 nautical miles
- Payload 30,000 lbs

### Mission Support Features

 Shirtsleeve environment for up to 30 researchers

- Worldwide deployment experience
- Extensive modifications to support in-situ and remote sensing instruments
  - zenith and nadir viewports
  - wing pylons
  - modified power systems
  - 19 inch rack mounting
- AIRSAR Discontinued



### **NASA Global Hawks**

• Two Advanced Concept Technology Demonstration (ACTD) aircraft transferred to NASA in September, 2007 (AV-1 and AV-6).

 Aircraft are based at the Armstrong Flight Research Center on Edwards Air Force Base.

 Configuration and performance similar to standard 'Block 10'.





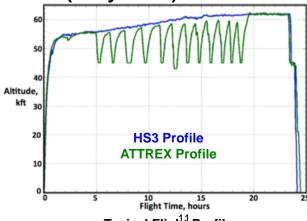
AV-6

# NASA Global Hawk Summary and Capability

- NASA has been flying Global Hawk aircraft for airborne Earth science research since 2010.
- The autonomous aircraft are remotely operated from either NASA Armstrong Flight Research Center, NASA Wallops Flight Facility, or a portable Flight Control Station.
- A NASA/Northrop Grumman team is maintaining, modifying, and operating the 2 ACTD aircraft through a partnership that was established in 2008 and renewed in 2013.

• Currently only AV6 is flying, and a Block 10 aircraft is being made operational using avionics and interfaces from AV1 (early FY17)

Endurance	24-26 hours for Typical Missions
	28.6 hours Demonstrated
Range	10,000 nmi
Service Ceiling	65,000 ft, < 50% available A/C payload power
	62,500 ft, > 50% available A/C payload power
Airspeed (55,000+ ft)	335 KTAS
Payload	1,200 lb Demonstrated
Length	44 ft
Wingspan	116 ft



Typical Flight Profiles

### **NASA Global Hawk Asset Overview**



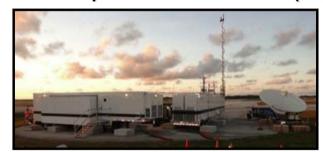
**Operational Aircraft** 



**Global Hawk Operations Center (AFRC)** 



**Global Hawk Operations Center – East (WFF)** 

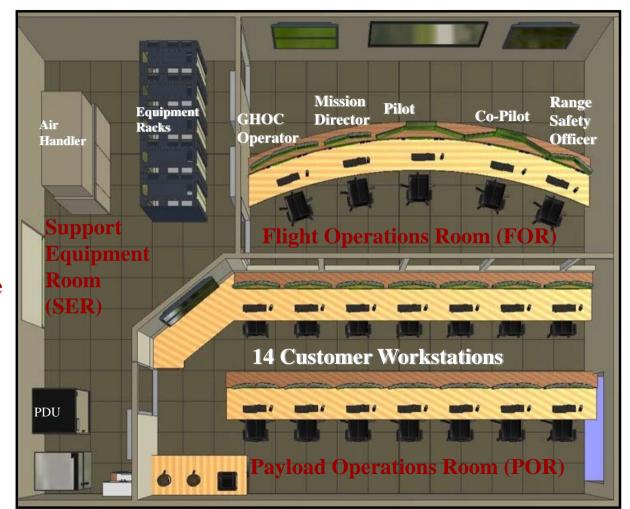


**Portable Ground Systems** 



**Spares Aircraft** 

# Global Hawk Operations Center (GHOC) Room Layout at NASA AFRC



Facility Entrance **GHOC Fully Staffed During a Hurricane Overflight** 

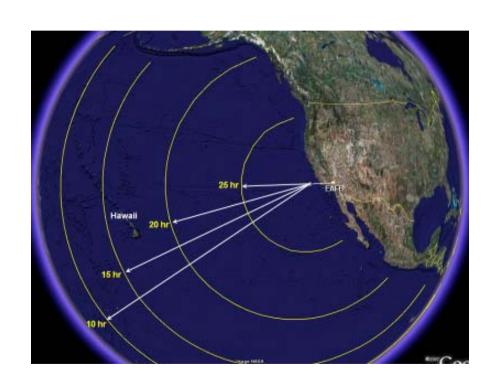


# Portable Ground Control Station Suite used for Deployed Operations





## Global Hawk time-on-station Based at EAFB



### Global Hawk Science Flights (1 of 2)

GloPac 2010

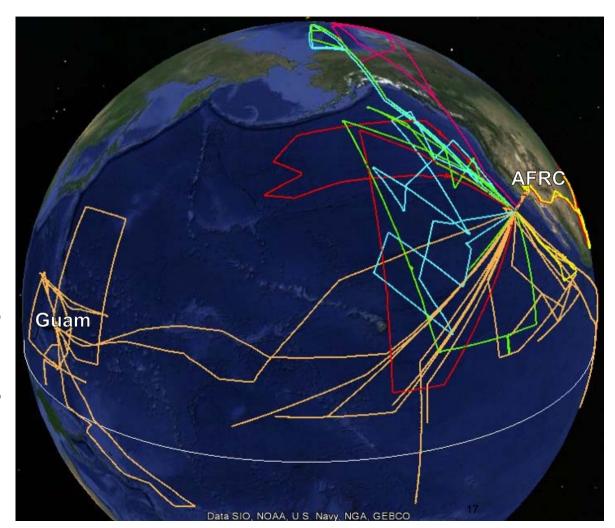
**GRIP 2010** 

WISPAR 2011

HS3 2011, 2012, 2013

**ATTREX 2011, 2013, 2014** 

IceHawk 2013



### Global Hawk Science Flights (2 of 2)

GloPac 2010

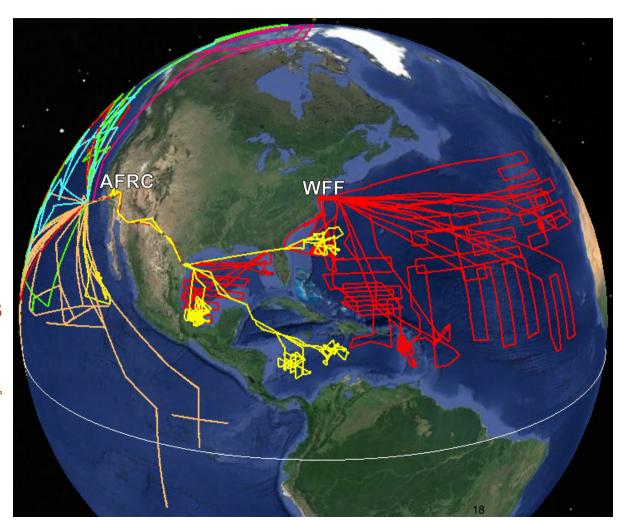
**GRIP 2010** 

WISPAR 2011

HS3 2011, 2012, 2013

**ATTREX** 2011, 2013, 2014

IceHawk 2013



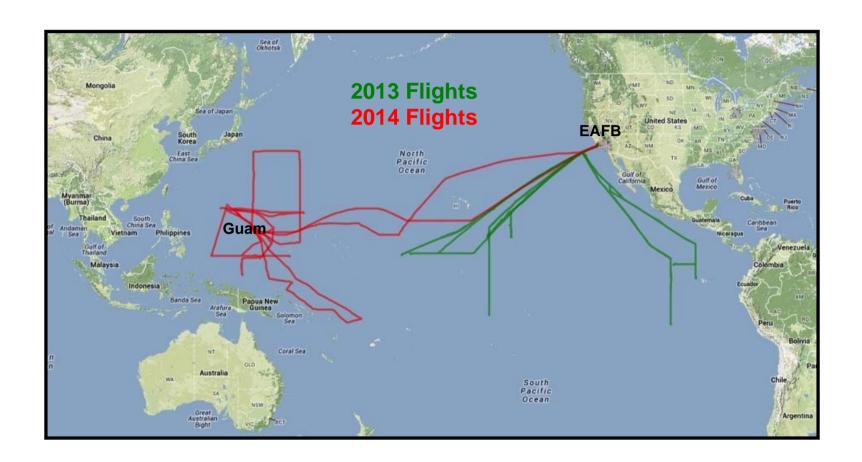
# Airborne Tropical Tropopause Experiment Overview

(October-November 2011, February-March 2013, January-March 2014)

- 11 instruments were flown on the NASA Global Hawk aircraft in 2011 and 2013 and 12 instruments were flown in 2014.
- 18 science missions, totaling 350 flight hours were flown during the 3 ATTREX campaigns.
- The flights in 2011 featured the first science demonstration in the tropics.
- The flights in 2014 featured the first OCONUS deployment for NASA Global Hawk.



## **ATTREX Flight Tracks**



### IceHawk

(December 2013)

- The UAV Synthetic Aperture Radar (UAVSAR) was integrated onto the aircraft.
- A single flight was conducted over the Pacific Ocean and Canada.
- This flight marked the first UAVSAR flight outside of the EAFB range and the first NASA Global Hawk flight over a foreign country.
- Coordination with the Canadian Government was straightforward.
- The IceHawk flight was funded by Northrop Grumman Co. as a platform capability demonstration-no instrument data were collected.



## **Options**

- G-III/UAVSAR is operational but limited flight time gives only a few passes over the target areas
- DC-8 has longer duration and ability to accommodate science team but UAVSAR has not been integrated
- Global Hawk has all the components necessary, but needs some component maturation as well as integration and testing of the fullup system
- All three platforms have satellite telemetry capability and telepresence, but large SAR files have not been demonstrated

## Discussion